

# Symplectic formalism and the covariant phase space on Scalar Electrodynamics

M. E. Rubio<sup>1,2</sup>, O. Reula<sup>1,2</sup>

## Junior scientist Andrejewski Days: 100 years of General Relativity

Begegnungsstätte Schloss Gollwitz  
Brandenburg an der Havel, Germany

April 2, 2015



<sup>1</sup>IFEG – CONICET  
<sup>2</sup>Facultad de Matemática, Astronomía y Física  
Universidad Nacional de Córdoba  
(5000) Córdoba, Argentina



- **PART I: The geometry of Classical Mechanics**
  - Symplectic formulation of Hamiltonian Mechanics
  - Symmetries and conserved quantities
  
- **PART II: Covariant phase space on field theories**
  - (Pre)–Symplectic structure and boundary conditions
  - Symmetries and conserved quantities
  
- **PART III: Scalar Electrodynamics**
  - Lagrangian, gauge symmetries and field equations
  - Symplectic structure and boundary conditions
  - Symmetries and conserved quantities

- **PART I: The geometry of Classical Mechanics**
  - Symplectic formulation of Hamiltonian Mechanics
  - Symmetries and conserved quantities
- **PART II: Covariant phase space on field theories**
  - (Pre)–Symplectic structure and boundary conditions
  - Symmetries and conserved quantities
- **PART III: Scalar Electrodynamics**
  - Lagrangian, gauge symmetries and field equations
  - Symplectic structure and boundary conditions
  - Symmetries and conserved quantities

- **PART I: The geometry of Classical Mechanics**
  - Symplectic formulation of Hamiltonian Mechanics
  - Symmetries and conserved quantities
- **PART II: Covariant phase space on field theories**
  - (Pre)–Symplectic structure and boundary conditions
  - Symmetries and conserved quantities
- **PART III: Scalar Electrodynamics**
  - Lagrangian, gauge symmetries and field equations
  - Symplectic structure and boundary conditions
  - Symmetries and conserved quantities

# PART I

## The geometry of Classical Mechanics

# Symplectic formulation of Hamiltonian Mechanics

- Any classical system with  $n$  degrees of freedom is characterized by a **Lagrangian**

$$\mathcal{L} = \mathcal{L}(q^i, \dot{q}^i, t),$$

where the coordinates  $q^i = q^i(t)$ . We introduce  $n$  covectors given by

$$p_i := \frac{\partial \mathcal{L}}{\partial \dot{q}^i}.$$

- Locally, the **phase space**  $\Gamma$  of the system is described by

$$(\{q^i\}, \{p_i\}), \quad i = 1, 2, \dots, n.$$

- The **Hamiltonian** of the system is a smooth function on  $\Gamma$ ,

$$\mathcal{H} : \Gamma \rightarrow \mathbb{R}, \quad \mathcal{H} := p_i \dot{q}^i - \mathcal{L},$$

and the **dynamics** of the system is described by

$$\dot{q}^i = \frac{\partial \mathcal{H}}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q^i}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Any classical system with  $n$  degrees of freedom is characterized by a **Lagrangian**

$$\mathcal{L} = \mathcal{L}(q^i, \dot{q}^i, t),$$

where the coordinates  $q^i = q^i(t)$ . We introduce  $n$  covectors given by

$$p_i := \frac{\partial \mathcal{L}}{\partial \dot{q}^i}.$$

- Locally, the **phase space**  $\Gamma$  of the system is described by

$$(\{q^i\}, \{p_i\}), \quad i = 1, 2, \dots, n.$$

- The **Hamiltonian** of the system is a smooth function on  $\Gamma$ ,

$$\mathcal{H} : \Gamma \rightarrow \mathbb{R}, \quad \mathcal{H} := p_i \dot{q}^i - \mathcal{L},$$

and the **dynamics** of the system is described by

$$\dot{q}^i = \frac{\partial \mathcal{H}}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q^i}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Any classical system with  $n$  degrees of freedom is characterized by a **Lagrangian**

$$\mathcal{L} = \mathcal{L}(q^i, \dot{q}^i, t),$$

where the coordinates  $q^i = q^i(t)$ . We introduce  $n$  covectors given by

$$p_i := \frac{\partial \mathcal{L}}{\partial \dot{q}^i}.$$

- Locally, the **phase space**  $\Gamma$  of the system is described by

$$(\{q^i\}, \{p_i\}), \quad i = 1, 2, \dots, n.$$

- The **Hamiltonian** of the system is a smooth function on  $\Gamma$ ,

$$\mathcal{H} : \Gamma \rightarrow \mathbb{R}, \quad \mathcal{H} := p_i \dot{q}^i - \mathcal{L},$$

and the **dynamics** of the system is described by

$$\boxed{\dot{q}^i = \frac{\partial \mathcal{H}}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q^i}}.$$



# Symplectic formulation of Hamiltonian Mechanics

- The phase space  $\Gamma$  seems to have some **intrinsic geometrical structure** related to the form of Hamilton equations.
- Let's introduce arbitrary coordinates  $x^\mu(q^i, p_i)$ ,  $\mu = 1, \dots, 2n$  on  $\Gamma$ . The evolution in the new coordinates is

$$\begin{aligned}\dot{x}^\mu &= \frac{\partial x^\mu}{\partial q^i} \dot{q}^i + \frac{\partial x^\mu}{\partial p_i} \dot{p}_i = \frac{\partial x^\mu}{\partial q^i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q^i} \\ &= \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) \frac{\partial \mathcal{H}}{\partial x^\nu} = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu};\end{aligned}$$

and thus,

$$\dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}, \quad \omega^{\mu\nu} := \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) = \{x^\mu, x^\nu\}.$$

# Symplectic formulation of Hamiltonian Mechanics

- The phase space  $\Gamma$  seems to have some **intrinsic geometrical structure** related to the form of Hamilton equations.
- Let's introduce arbitrary coordinates  $x^\mu(q^i, p_i)$ ,  $\mu = 1, \dots, 2n$  on  $\Gamma$ . The evolution in the new coordinates is

$$\begin{aligned}\dot{x}^\mu &= \frac{\partial x^\mu}{\partial q^i} \dot{q}^i + \frac{\partial x^\mu}{\partial p_i} \dot{p}_i = \frac{\partial x^\mu}{\partial q^i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q^i} \\ &= \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) \frac{\partial \mathcal{H}}{\partial x^\nu} = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu};\end{aligned}$$

and thus,

$$\dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}, \quad \omega^{\mu\nu} := \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) = \{x^\mu, x^\nu\}.$$

# Symplectic formulation of Hamiltonian Mechanics

- The phase space  $\Gamma$  seems to have some **intrinsic geometrical structure** related to the form of Hamilton equations.
- Let's introduce arbitrary coordinates  $x^\mu(q^i, p_i)$ ,  $\mu = 1, \dots, 2n$  on  $\Gamma$ . The evolution in the new coordinates is

$$\begin{aligned}\dot{x}^\mu &= \frac{\partial x^\mu}{\partial q^i} \dot{q}^i + \frac{\partial x^\mu}{\partial p_i} \dot{p}_i = \frac{\partial x^\mu}{\partial q^i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q^i} \\ &= \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) \frac{\partial \mathcal{H}}{\partial x^\nu} = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu};\end{aligned}$$

and thus,

$$\dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}, \quad \omega^{\mu\nu} := \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) = \{x^\mu, x^\nu\}.$$

# Symplectic formulation of Hamiltonian Mechanics

- The phase space  $\Gamma$  seems to have some **intrinsic geometrical structure** related to the form of Hamilton equations.
- Let's introduce arbitrary coordinates  $x^\mu(q^i, p_i)$ ,  $\mu = 1, \dots, 2n$  on  $\Gamma$ . The evolution in the new coordinates is

$$\begin{aligned}\dot{x}^\mu &= \frac{\partial x^\mu}{\partial q^i} \dot{q}^i + \frac{\partial x^\mu}{\partial p_i} \dot{p}_i = \frac{\partial x^\mu}{\partial q^i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q^i} \\ &= \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) \frac{\partial \mathcal{H}}{\partial x^\nu} = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu};\end{aligned}$$

and thus,

$$\dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}, \quad \omega^{\mu\nu} := \left( \frac{\partial x^\mu}{\partial q^i} \frac{\partial x^\nu}{\partial p_i} - \frac{\partial x^\mu}{\partial p_i} \frac{\partial x^\nu}{\partial q^i} \right) = \{x^\mu, x^\nu\}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to [Hamilton Equations](#).

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the [Poisson bracket](#)  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to [Hamilton Equations](#).

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the [Poisson bracket](#)  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to [Hamilton Equations](#).

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the [Poisson bracket](#)  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to [Hamilton Equations](#).

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the [Poisson bracket](#)  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$



# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to **Hamilton Equations**.

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the **Poisson bracket**  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Properties of  $\omega^{\mu\nu}$ :

$$\omega^{\mu\nu} = -\omega^{\nu\mu}; \quad (1)$$

$$\det(\omega^{\mu\nu}) = \left| \frac{\partial x^\mu}{\partial(q^i, p_j)} \right|^2 \neq 0; \quad (2)$$

$$\partial_{[\mu} \omega_{\nu\rho]} = 0. \quad (3)$$

- In particular, if  $(x^1, \dots, x^{2n}) = (q^1, \dots, q^n, p_1, \dots, p_n)$ ,

$$\omega^{\mu\nu} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix},$$

and we return to [Hamilton Equations](#).

- If  $f : \Gamma \rightarrow \mathbb{R}$  and  $g : \Gamma \rightarrow \mathbb{R}$ , we redefine the [Poisson bracket](#)  $\{f, g\}$  in terms of  $\omega$ :

$$\{f, g\} := \omega^{\mu\nu} \frac{\partial f}{\partial x^\mu} \frac{\partial g}{\partial x^\nu}.$$

# Symplectic formulation of Hamiltonian Mechanics

- Fixing  $g$ ,  $\{f, g\}$  is a **derivation** on  $f$  along the vector

$$X_g^\mu := \omega^{\mu\nu} \frac{\partial g}{\partial x^\nu}.$$

This vector field is called **Hamiltonian vector field**.

- The inverse of  $\omega^{\mu\nu}$ ,  $\omega_{\mu\nu}$  is called **symplectic structure**.
- A **symplectic manifold** is a pair  $(\mathcal{M}, \omega)$  such that  $\omega$  satisfies (1), (2) and (3).
- Note that (3) implies that  $\omega_{\mu\nu}$  is a **closed non degenerate 2-form**.
- **Darboux's Theorem**: Let  $(\Gamma, \omega)$  be a symplectic manifold. Then, for each point  $p \in \Gamma$ , there exists a neighbourhood of  $p$  and a chart  $(\{q^i\}, \{p_i\})$  such that

$$\omega = dp_i \wedge dq^i = d(p_i dq^i).$$

# Symplectic formulation of Hamiltonian Mechanics

- Fixing  $g$ ,  $\{f, g\}$  is a **derivation** on  $f$  along the vector

$$X_g^\mu := \omega^{\mu\nu} \frac{\partial g}{\partial x^\nu}.$$

This vector field is called **Hamiltonian vector field**.

- The inverse of  $\omega^{\mu\nu}$ ,  $\omega_{\mu\nu}$  is called **symplectic structure**.
- A **symplectic manifold** is a pair  $(\mathcal{M}, \omega)$  such that  $\omega$  satisfies (1), (2) and (3).
- Note that (3) implies that  $\omega_{\mu\nu}$  is a **closed non degenerate 2-form**.
- **Darboux's Theorem**: Let  $(\Gamma, \omega)$  be a symplectic manifold. Then, for each point  $p \in \Gamma$ , there exists a neighbourhood of  $p$  and a chart  $(\{q^i\}, \{p_i\})$  such that

$$\omega = dp_i \wedge dq^i = d(p_i dq^i).$$

# Symplectic formulation of Hamiltonian Mechanics

- Fixing  $g$ ,  $\{f, g\}$  is a **derivation** on  $f$  along the vector

$$X_g^\mu := \omega^{\mu\nu} \frac{\partial g}{\partial x^\nu}.$$

This vector field is called **Hamiltonian vector field**.

- The inverse of  $\omega^{\mu\nu}$ ,  $\omega_{\mu\nu}$  is called **symplectic structure**.
- A **symplectic manifold** is a pair  $(\mathcal{M}, \omega)$  such that  $\omega$  satisfies (1), (2) and (3).
- Note that (3) implies that  $\omega_{\mu\nu}$  is a **closed non degenerate 2-form**.
- **Darboux's Theorem**: Let  $(\Gamma, \omega)$  be a symplectic manifold. Then, for each point  $p \in \Gamma$ , there exists a neighbourhood of  $p$  and a chart  $(\{q^i\}, \{p_i\})$  such that

$$\omega = dp_i \wedge dq^i = d(p_i dq^i).$$

# Symplectic formulation of Hamiltonian Mechanics

- Fixing  $g$ ,  $\{f, g\}$  is a **derivation** on  $f$  along the vector

$$X_g^\mu := \omega^{\mu\nu} \frac{\partial g}{\partial x^\nu}.$$

This vector field is called **Hamiltonian vector field**.

- The inverse of  $\omega^{\mu\nu}$ ,  $\omega_{\mu\nu}$  is called **symplectic structure**.
- A **symplectic manifold** is a pair  $(\mathcal{M}, \omega)$  such that  $\omega$  satisfies (1), (2) and (3).
- Note that (3) implies that  $\omega_{\mu\nu}$  is a **closed non degenerate 2-form**.
- **Darboux's Theorem**: Let  $(\Gamma, \omega)$  be a symplectic manifold. Then, for each point  $p \in \Gamma$ , there exists a neighbourhood of  $p$  and a chart  $(\{q^i\}, \{p_i\})$  such that

$$\omega = dp_i \wedge dq^i = d(p_i dq^i).$$

# Symplectic formulation of Hamiltonian Mechanics

- Fixing  $g$ ,  $\{f, g\}$  is a **derivation** on  $f$  along the vector

$$X_g^\mu := \omega^{\mu\nu} \frac{\partial g}{\partial x^\nu}.$$

This vector field is called **Hamiltonian vector field**.

- The inverse of  $\omega^{\mu\nu}$ ,  $\omega_{\mu\nu}$  is called **symplectic structure**.
- A **symplectic manifold** is a pair  $(\mathcal{M}, \omega)$  such that  $\omega$  satisfies (1), (2) and (3).
- Note that (3) implies that  $\omega_{\mu\nu}$  is a **closed non degenerate 2-form**.
- **Darboux's Theorem:** Let  $(\Gamma, \omega)$  be a symplectic manifold. Then, for each point  $p \in \Gamma$ , there exists a neighbourhood of  $p$  and a chart  $(\{q^i\}, \{p_i\})$  such that

$$\omega = dp_i \wedge dq^i = d(p_i dq^i).$$

# Symmetries and conserved quantities

- **Symmetry?**  $\Phi : \Gamma \rightarrow \Gamma$  smooth and invertible, that takes a *solution* and produces *another*.
- **Solution?** Curve  $\gamma : I \subseteq \mathbb{R} \rightarrow \Gamma$ ,  $t \mapsto \gamma(t)$  such that

$$\dot{\gamma} = X_{\mathcal{H}}, \quad \dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}.$$

- If  $\{\Phi_s\}_{s \in \mathbb{R}}$  is a **monoparametric family of symmetries** and  $p \in \Gamma$ , let's consider the curve  $s \mapsto \gamma_p(s) := \Phi_s(p)$ . The **tangent vector**

$$\xi := \left. \frac{d\Phi_s(p)}{ds} \right|_{s=0}$$

is called an **infinitesimal transformation** of  $\Phi$  at  $p$ .

- The fields  $X_{\mathcal{H}}$  and  $\xi$  generate a 2-dimensional submanifold on  $\Gamma$ , and must be **coordinate vector fields**:

$$0 = [\xi, X_{\mathcal{H}}]^\mu = X_{\xi(\mathcal{H})}^\mu + (\mathcal{L}_\xi \omega^{\mu\nu}) \frac{\partial \mathcal{H}}{\partial x^\nu} \Rightarrow \boxed{\mathcal{L}_\xi \omega = 0}$$



# Symmetries and conserved quantities

- **Symmetry?**  $\Phi : \Gamma \rightarrow \Gamma$  smooth and invertible, that takes a *solution* and produces *another*.
- **Solution?** Curve  $\gamma : I \subseteq \mathbb{R} \rightarrow \Gamma$ ,  $t \mapsto \gamma(t)$  such that

$$\dot{\gamma} = X_{\mathcal{H}}, \quad \dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}.$$

- If  $\{\Phi_s\}_{s \in \mathbb{R}}$  is a **monoparametric family of symmetries** and  $p \in \Gamma$ , let's consider the curve  $s \mapsto \gamma_p(s) := \Phi_s(p)$ . The **tangent vector**

$$\xi := \left. \frac{d\Phi_s(p)}{ds} \right|_{s=0}$$

is called an **infinitesimal transformation** of  $\Phi$  at  $p$ .

- The fields  $X_{\mathcal{H}}$  and  $\xi$  generate a 2-dimensional submanifold on  $\Gamma$ , and must be **coordinate vector fields**:

$$0 = [\xi, X_{\mathcal{H}}]^\mu = X_{\xi(\mathcal{H})}^\mu + (\mathcal{L}_\xi \omega^{\mu\nu}) \frac{\partial \mathcal{H}}{\partial x^\nu} \Rightarrow \boxed{\mathcal{L}_\xi \omega = 0}$$

# Symmetries and conserved quantities

- **Symmetry?**  $\Phi : \Gamma \rightarrow \Gamma$  smooth and invertible, that takes a *solution* and produces *another*.
- **Solution?** Curve  $\gamma : I \subseteq \mathbb{R} \rightarrow \Gamma$ ,  $t \mapsto \gamma(t)$  such that

$$\dot{\gamma} = X_{\mathcal{H}}, \quad \dot{x}^{\mu} = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^{\nu}}.$$

- If  $\{\Phi_s\}_{s \in \mathbb{R}}$  is a **monoparametric family of symmetries** and  $p \in \Gamma$ , let's consider the curve  $s \mapsto \gamma_p(s) := \Phi_s(p)$ . The **tangent vector**

$$\xi := \left. \frac{d\Phi_s(p)}{ds} \right|_{s=0}$$

is called an **infinitesimal transformation** of  $\Phi$  at  $p$ .

- The fields  $X_{\mathcal{H}}$  and  $\xi$  generate a 2-dimensional submanifold on  $\Gamma$ , and must be **coordinate vector fields**:

$$0 = [\xi, X_{\mathcal{H}}]^{\mu} = X_{\xi(\mathcal{H})}^{\mu} + (\mathcal{L}_{\xi} \omega^{\mu\nu}) \frac{\partial \mathcal{H}}{\partial x^{\nu}} \Rightarrow \boxed{\mathcal{L}_{\xi} \omega = 0}$$

# Symmetries and conserved quantities

- **Symmetry?**  $\Phi : \Gamma \rightarrow \Gamma$  smooth and invertible, that takes a *solution* and produces *another*.
- **Solution?** Curve  $\gamma : I \subseteq \mathbb{R} \rightarrow \Gamma$ ,  $t \mapsto \gamma(t)$  such that

$$\dot{\gamma} = X_{\mathcal{H}}, \quad \dot{x}^\mu = \omega^{\mu\nu} \frac{\partial \mathcal{H}}{\partial x^\nu}.$$

- If  $\{\Phi_s\}_{s \in \mathbb{R}}$  is a **monoparametric family of symmetries** and  $p \in \Gamma$ , let's consider the curve  $s \mapsto \gamma_p(s) := \Phi_s(p)$ . The **tangent vector**

$$\xi := \left. \frac{d\Phi_s(p)}{ds} \right|_{s=0}$$

is called an **infinitesimal transformation** of  $\Phi$  at  $p$ .

- The fields  $X_{\mathcal{H}}$  and  $\xi$  generate a 2-dimensional submanifold on  $\Gamma$ , and must be **coordinate vector fields**:

$$0 = [\xi, X_{\mathcal{H}}]^\mu = X_{\xi(\mathcal{H})}^\mu + (\mathcal{L}_\xi \omega^{\mu\nu}) \frac{\partial \mathcal{H}}{\partial x^\nu} \Rightarrow \boxed{\mathcal{L}_\xi \omega = 0}$$

# PART II

## Covariant Phase Space on Field Theories

# Covariant Phase Space on Field Theories

- Consider a smooth 4-dimensional lorentzian manifold  $\mathcal{M}$  with the topology of  $\Sigma \times \mathbb{R}$  and  $\Sigma \equiv \mathbb{R}^3$ .
- $\mathcal{M}$  is equipped with a **stationary** and **globally hyperbolic** metric  $g_{ab}$  such that Cauchy surfaces are diffeomorphic to  $\Sigma$ .
- On this spacetime, consider a **dynamical theory** for a collection of fields  $\phi^\alpha(x)$ , where  $\alpha$  labels the fields. We denote

$$\mathcal{F} := \{\phi^\alpha : \mathcal{M} \rightarrow \mathcal{T}_{\mathcal{M}}^{(k,l)\alpha} \mid \phi^\alpha \text{ satisfy some boundary conditions}\}.$$

- $\mathcal{F}$  has the structure of an **infinite-dimensional manifold**. Functions on  $\mathcal{F}$  are functionals  $f : \mathcal{F} \rightarrow \mathbb{R}$ .
- Dynamics is specified by some **action**  $\mathcal{S}_V$ , defined over any measurable region  $V \subset \mathcal{M}$ :

$$\mathcal{S}_V(\phi^\alpha) = \int_V \mathcal{L}(\phi^\alpha, \nabla_a \phi^\alpha, \nabla_a \nabla_b \phi^\alpha, \dots) dV.$$

# Covariant Phase Space on Field Theories

- Consider a smooth 4-dimensional lorentzian manifold  $\mathcal{M}$  with the topology of  $\Sigma \times \mathbb{R}$  and  $\Sigma \equiv \mathbb{R}^3$ .
- $\mathcal{M}$  is equipped with a **stationary** and **globally hyperbolic** metric  $g_{ab}$  such that Cauchy surfaces are diffeomorphic to  $\Sigma$ .
- On this spacetime, consider a **dynamical theory** for a collection of fields  $\phi^\alpha(x)$ , where  $\alpha$  labels the fields. We denote

$$\mathcal{F} := \{\phi^\alpha : \mathcal{M} \rightarrow \mathcal{T}_{\mathcal{M}}^{(k,l)\alpha} \mid \phi^\alpha \text{ satisfy some boundary conditions}\}.$$

- $\mathcal{F}$  has the structure of an **infinite-dimensional manifold**. Functions on  $\mathcal{F}$  are functionals  $f : \mathcal{F} \rightarrow \mathbb{R}$ .
- Dynamics is specified by some **action**  $\mathcal{S}_V$ , defined over any measurable region  $V \subset \mathcal{M}$ :

$$\mathcal{S}_V(\phi^\alpha) = \int_V \mathcal{L}(\phi^\alpha, \nabla_a \phi^\alpha, \nabla_a \nabla_b \phi^\alpha, \dots) dV.$$

# Covariant Phase Space on Field Theories

- Consider a smooth 4-dimensional lorentzian manifold  $\mathcal{M}$  with the topology of  $\Sigma \times \mathbb{R}$  and  $\Sigma \equiv \mathbb{R}^3$ .
- $\mathcal{M}$  is equipped with a **stationary** and **globally hyperbolic** metric  $g_{ab}$  such that Cauchy surfaces are diffeomorphic to  $\Sigma$ .
- On this spacetime, consider a **dynamical theory** for a collection of fields  $\phi^\alpha(x)$ , where  $\alpha$  labels the fields. We denote

$$\mathcal{F} := \{\phi^\alpha : \mathcal{M} \rightarrow \mathcal{T}_{\mathcal{M}}^{(k,l)\alpha} \mid \phi^\alpha \text{ satisfy some boundary conditions}\}.$$

- $\mathcal{F}$  has the structure of an **infinite-dimensional manifold**. Functions on  $\mathcal{F}$  are functionals  $f : \mathcal{F} \rightarrow \mathbb{R}$ .
- Dynamics is specified by some **action**  $\mathcal{S}_V$ , defined over any measurable region  $V \subset \mathcal{M}$ :

$$\mathcal{S}_V(\phi^\alpha) = \int_V \mathcal{L}(\phi^\alpha, \nabla_a \phi^\alpha, \nabla_a \nabla_b \phi^\alpha, \dots) dV.$$

# Covariant Phase Space on Field Theories

- Consider a smooth 4-dimensional lorentzian manifold  $\mathcal{M}$  with the topology of  $\Sigma \times \mathbb{R}$  and  $\Sigma \equiv \mathbb{R}^3$ .
- $\mathcal{M}$  is equipped with a **stationary** and **globally hyperbolic** metric  $g_{ab}$  such that Cauchy surfaces are diffeomorphic to  $\Sigma$ .
- On this spacetime, consider a **dynamical theory** for a collection of fields  $\phi^\alpha(x)$ , where  $\alpha$  labels the fields. We denote

$$\mathcal{F} := \{\phi^\alpha : \mathcal{M} \rightarrow \mathcal{T}_{\mathcal{M}}^{(k,l)\alpha} \mid \phi^\alpha \text{ satisfy some boundary conditions}\}.$$

- $\mathcal{F}$  has the structure of an **infinite-dimensional manifold**. Functions on  $\mathcal{F}$  are functionals  $f : \mathcal{F} \rightarrow \mathbb{R}$ .
- Dynamics is specified by some **action**  $\mathcal{S}_V$ , defined over any measurable region  $V \subset \mathcal{M}$ :

$$\mathcal{S}_V(\phi^\alpha) = \int_V \mathcal{L}(\phi^\alpha, \nabla_a \phi^\alpha, \nabla_a \nabla_b \phi^\alpha, \dots) dV.$$



# Covariant Phase Space on Field Theories

- Consider a smooth 4-dimensional lorentzian manifold  $\mathcal{M}$  with the topology of  $\Sigma \times \mathbb{R}$  and  $\Sigma \equiv \mathbb{R}^3$ .
- $\mathcal{M}$  is equipped with a **stationary** and **globally hyperbolic** metric  $g_{ab}$  such that Cauchy surfaces are diffeomorphic to  $\Sigma$ .
- On this spacetime, consider a **dynamical theory** for a collection of fields  $\phi^\alpha(x)$ , where  $\alpha$  labels the fields. We denote

$$\mathcal{F} := \{\phi^\alpha : \mathcal{M} \rightarrow \mathcal{T}_{\mathcal{M}}^{(k,l)\alpha} \mid \phi^\alpha \text{ satisfy some boundary conditions}\}.$$

- $\mathcal{F}$  has the structure of an **infinite-dimensional manifold**. Functions on  $\mathcal{F}$  are functionals  $f : \mathcal{F} \rightarrow \mathbb{R}$ .
- Dynamics is specified by some **action**  $\mathcal{S}_V$ , defined over any measurable region  $V \subset \mathcal{M}$ :

$$\mathcal{S}_V(\phi^\alpha) = \int_V \mathcal{L}(\phi^\alpha, \nabla_a \phi^\alpha, \nabla_a \nabla_b \phi^\alpha, \dots) dV.$$

# Covariant Phase Space on Field Theories

- We require that  $\mathcal{S}_V$  be **stationary** under any variation  $\delta\phi^\alpha$  such that  $\delta\phi^\alpha|_{\partial V} = 0$ .
- If  $\mathcal{L}$  contains terms which are pure divergences, then  $\mathcal{S}_V$  must have surface terms. For example, if the action is of **first order**, then  $\mathcal{L}(\phi^\alpha, \nabla_a\phi^\alpha)$ , and the variation is

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \left( \frac{\partial\mathcal{L}}{\partial\phi^\alpha} - \nabla_a \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \right) \delta\phi^\alpha dV + \oint_{\partial V} \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \delta\phi^\alpha dS_a.$$

- A **general variation** of  $\mathcal{S}_V$  will be of the form

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \mathcal{G}_\alpha(\phi) \delta\phi^\alpha dV + \oint_{\partial V} F^a(\phi^\alpha, \delta\phi^\alpha) dS_a.$$

- $\mathcal{G}_\alpha$  depends on derivatives **up to second order** of  $\phi^\alpha$ , and  $F^a = 0$  when  $\delta\phi^\alpha = 0$  at  $\partial V$ ; so fields equations are

$$\mathcal{G}_\alpha(\phi) = 0$$

# Covariant Phase Space on Field Theories

- We require that  $\mathcal{S}_V$  be **stationary** under any variation  $\delta\phi^\alpha$  such that  $\delta\phi^\alpha|_{\partial V} = 0$ .
- If  $\mathcal{L}$  contains terms which are pure divergences, then  $\mathcal{S}_V$  must have surface terms. For example, if the action is of **first order**, then  $\mathcal{L}(\phi^\alpha, \nabla_a\phi^\alpha)$ , and the variation is

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \left( \frac{\partial\mathcal{L}}{\partial\phi^\alpha} - \nabla_a \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \right) \delta\phi^\alpha dV + \oint_{\partial V} \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \delta\phi^\alpha dS_a.$$

- A **general variation** of  $\mathcal{S}_V$  will be of the form

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \mathcal{G}_\alpha(\phi) \delta\phi^\alpha dV + \oint_{\partial V} F^a(\phi^\alpha, \delta\phi^\alpha) dS_a.$$

- $\mathcal{G}_\alpha$  depends on derivatives **up to second order** of  $\phi^\alpha$ , and  $F^a = 0$  when  $\delta\phi^\alpha = 0$  at  $\partial V$ ; so fields equations are

$$\mathcal{G}_\alpha(\phi) = 0$$

# Covariant Phase Space on Field Theories

- We require that  $\mathcal{S}_V$  be **stationary** under any variation  $\delta\phi^\alpha$  such that  $\delta\phi^\alpha|_{\partial V} = 0$ .
- If  $\mathcal{L}$  contains terms which are pure divergences, then  $\mathcal{S}_V$  must have surface terms. For example, if the action is of **first order**, then  $\mathcal{L}(\phi^\alpha, \nabla_a\phi^\alpha)$ , and the variation is

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \left( \frac{\partial\mathcal{L}}{\partial\phi^\alpha} - \nabla_a \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \right) \delta\phi^\alpha dV + \oint_{\partial V} \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \delta\phi^\alpha dS_a.$$

- A **general variation** of  $\mathcal{S}_V$  will be of the form

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \mathcal{G}_\alpha(\phi) \delta\phi^\alpha dV + \oint_{\partial V} F^a(\phi^\alpha, \delta\phi^\alpha) dS_a.$$

- $\mathcal{G}_\alpha$  depends on derivatives **up to second order** of  $\phi^\alpha$ , and  $F^a = 0$  when  $\delta\phi^\alpha = 0$  at  $\partial V$ ; so fields equations are

$$\mathcal{G}_\alpha(\phi) = 0$$

# Covariant Phase Space on Field Theories

- We require that  $\mathcal{S}_V$  be **stationary** under any variation  $\delta\phi^\alpha$  such that  $\delta\phi^\alpha|_{\partial V} = 0$ .
- If  $\mathcal{L}$  contains terms which are pure divergences, then  $\mathcal{S}_V$  must have surface terms. For example, if the action is of **first order**, then  $\mathcal{L}(\phi^\alpha, \nabla_a\phi^\alpha)$ , and the variation is

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \left( \frac{\partial\mathcal{L}}{\partial\phi^\alpha} - \nabla_a \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \right) \delta\phi^\alpha dV + \oint_{\partial V} \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \delta\phi^\alpha dS_a.$$

- A **general variation** of  $\mathcal{S}_V$  will be of the form

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \mathcal{G}_\alpha(\phi) \delta\phi^\alpha dV + \oint_{\partial V} F^a(\phi^\alpha, \delta\phi^\alpha) dS_a.$$

- $\mathcal{G}_\alpha$  depends on derivatives **up to second order** of  $\phi^\alpha$ , and  $F^a = 0$  when  $\delta\phi^\alpha = 0$  at  $\partial V$ ; so fields equations are

$$\mathcal{G}_\alpha(\phi) = 0$$

# Covariant Phase Space on Field Theories

- We require that  $\mathcal{S}_V$  be **stationary** under any variation  $\delta\phi^\alpha$  such that  $\delta\phi^\alpha|_{\partial V} = 0$ .
- If  $\mathcal{L}$  contains terms which are pure divergences, then  $\mathcal{S}_V$  must have surface terms. For example, if the action is of **first order**, then  $\mathcal{L}(\phi^\alpha, \nabla_a\phi^\alpha)$ , and the variation is

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \left( \frac{\partial\mathcal{L}}{\partial\phi^\alpha} - \nabla_a \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \right) \delta\phi^\alpha dV + \oint_{\partial V} \frac{\partial\mathcal{L}}{\partial\nabla_a\phi^\alpha} \delta\phi^\alpha dS_a.$$

- A **general variation** of  $\mathcal{S}_V$  will be of the form

$$d\mathcal{S}_V(\delta\phi^\alpha) = \int_V \mathcal{G}_\alpha(\phi) \delta\phi^\alpha dV + \oint_{\partial V} F^a(\phi^\alpha, \delta\phi^\alpha) dS_a.$$

- $\mathcal{G}_\alpha$  depends on derivatives **up to second order** of  $\phi^\alpha$ , and  $F^a = 0$  when  $\delta\phi^\alpha = 0$  at  $\partial V$ ; so fields equations are

$$\mathcal{G}_\alpha(\phi) = 0$$

# Covariant Phase Space on Field Theories

- The **covariant phase space** of the theory is the submanifold  $\Gamma \subset \mathcal{F}$  given by

$$\Gamma = \{\phi^\alpha \in \mathcal{F} \mid \mathcal{G}_\alpha(\phi) = 0\}.$$

- Given a Cauchy surface  $\Sigma$ , we define the **potential 1-form**  $\theta_\Sigma$  on  $\Gamma$  as

$$\theta_\Sigma(X) := \int_\Sigma F^a(\phi, X) dS_a,$$

where  $X$  is **any vector field** on  $\Gamma$ .

## Definition

The **pre-symplectic structure** of the theory is

$$\omega_\Sigma(X, Y) := d\theta_\Sigma(X, Y).$$

- By construction,  $d\omega = 0$ .
- $\omega$  does not depend on the choice of  $\Sigma$ .

# Covariant Phase Space on Field Theories

- The **covariant phase space** of the theory is the submanifold  $\Gamma \subset \mathcal{F}$  given by

$$\Gamma = \{\phi^\alpha \in \mathcal{F} \mid \mathcal{G}_\alpha(\phi) = 0\}.$$

- Given a Cauchy surface  $\Sigma$ , we define the **potential 1-form**  $\theta_\Sigma$  on  $\Gamma$  as

$$\theta_\Sigma(X) := \int_\Sigma F^a(\phi, X) dS_a,$$

where  $X$  is **any vector field** on  $\Gamma$ .

## Definition

The **pre-symplectic structure** of the theory is

$$\omega_\Sigma(X, Y) := d\theta_\Sigma(X, Y).$$

- By construction,  $d\omega = 0$ .
- $\omega$  does not depend on the choice of  $\Sigma$ .



# Covariant Phase Space on Field Theories

- The **covariant phase space** of the theory is the submanifold  $\Gamma \subset \mathcal{F}$  given by

$$\Gamma = \{\phi^\alpha \in \mathcal{F} \mid \mathcal{G}_\alpha(\phi) = 0\}.$$

- Given a Cauchy surface  $\Sigma$ , we define the **potential 1-form**  $\theta_\Sigma$  on  $\Gamma$  as

$$\theta_\Sigma(X) := \int_\Sigma F^a(\phi, X) dS_a,$$

where  $X$  is **any vector field** on  $\Gamma$ .

## Definition

The **pre-symplectic structure** of the theory is

$$\omega_\Sigma(X, Y) := d\theta_\Sigma(X, Y).$$

- By construction,  $d\omega = 0$ .
- $\omega$  does not depend on the choice of  $\Sigma$ .

# Covariant Phase Space on Field Theories

- The **covariant phase space** of the theory is the submanifold  $\Gamma \subset \mathcal{F}$  given by

$$\Gamma = \{\phi^\alpha \in \mathcal{F} \mid \mathcal{G}_\alpha(\phi) = 0\}.$$

- Given a Cauchy surface  $\Sigma$ , we define the **potential 1-form**  $\theta_\Sigma$  on  $\Gamma$  as

$$\theta_\Sigma(X) := \int_\Sigma F^a(\phi, X) dS_a,$$

where  $X$  is **any vector field** on  $\Gamma$ .

## Definition

The **pre-symplectic structure** of the theory is

$$\omega_\Sigma(X, Y) := d\theta_\Sigma(X, Y).$$

- By construction,  $d\omega = 0$ .
- $\omega$  does not depend on the choice of  $\Sigma$ .

# Covariant Phase Space on Field Theories

- The **covariant phase space** of the theory is the submanifold  $\Gamma \subset \mathcal{F}$  given by

$$\Gamma = \{\phi^\alpha \in \mathcal{F} \mid \mathcal{G}_\alpha(\phi) = 0\}.$$

- Given a Cauchy surface  $\Sigma$ , we define the **potential 1-form**  $\theta_\Sigma$  on  $\Gamma$  as

$$\theta_\Sigma(X) := \int_\Sigma F^a(\phi, X) dS_a,$$

where  $X$  is **any vector field** on  $\Gamma$ .

## Definition

The **pre-symplectic structure** of the theory is

$$\omega_\Sigma(X, Y) := d\theta_\Sigma(X, Y).$$

- By construction,  $d\omega = 0$ .
- $\omega$  does not depend on the choice of  $\Sigma$ .

# (Pre)–Symplectic structure

- If  $V$  is bounded by two Cauchy surfaces  $\Sigma$  and  $\Sigma'$  connected by some region  $\mathcal{K}_\infty \subset i^0$ , a variation  $d\mathcal{S}_V$  around a solution is

$$i^*d\mathcal{S}_V = \theta_{\Sigma'} - \theta_\Sigma + \theta_{\mathcal{K}_\infty}, \quad i : \Gamma \rightarrow \mathcal{F}.$$

- Taking the exterior derivative, we get

$$0 = i^*d^2\mathcal{S}_V = d(i^*d\mathcal{S}_V) = \omega_{\Sigma'} - \omega_\Sigma + \omega_{\mathcal{K}_\infty}.$$

- Choosing boundary conditions such that  $\omega_{\mathcal{K}_\infty} = 0$ ,  $\omega$  is independent of the Cauchy surface.
- In general,  $\omega$  is degenerate. If  $X, X' \in \text{Ker}(\omega)$ ,

$$\begin{aligned} 0 &= \mathcal{L}_{X'}\omega(X, Y) = \omega(\mathcal{L}_{X'}X, Y) + \omega(X, \mathcal{L}_{X'}Y) \\ &= \omega([X', X], Y). \end{aligned}$$

so  $\text{Ker}(\omega)$  is integrable and one can quotient  $\Gamma$  by the integral manifolds of  $\text{Ker}(\omega)$  and obtain a non-degenerate symplectic structure defined on

$$\Gamma / \{\text{integral manifold of } \text{Ker}(\omega)\}.$$

# (Pre)–Symplectic structure

- If  $V$  is bounded by two Cauchy surfaces  $\Sigma$  and  $\Sigma'$  connected by some region  $\mathcal{K}_\infty \subset i^0$ , a variation  $d\mathcal{S}_V$  around a solution is

$$i^*d\mathcal{S}_V = \theta_{\Sigma'} - \theta_\Sigma + \theta_{\mathcal{K}_\infty}, \quad i : \Gamma \rightarrow \mathcal{F}.$$

- Taking the exterior derivative, we get

$$0 = i^*d^2\mathcal{S}_V = d(i^*d\mathcal{S}_V) = \omega_{\Sigma'} - \omega_\Sigma + \omega_{\mathcal{K}_\infty}.$$

- Choosing boundary conditions such that  $\omega_{\mathcal{K}_\infty} = 0$ ,  $\omega$  is independent of the Cauchy surface.
- In general,  $\omega$  is degenerate. If  $X, X' \in \text{Ker}(\omega)$ ,

$$\begin{aligned} 0 &= \mathcal{L}_{X'}\omega(X, Y) = \omega(\mathcal{L}_{X'}X, Y) + \omega(X, \mathcal{L}_{X'}Y) \\ &= \omega([X', X], Y). \end{aligned}$$

so  $\text{Ker}(\omega)$  is integrable and one can quotient  $\Gamma$  by the integral manifolds of  $\text{Ker}(\omega)$  and obtain a non-degenerate symplectic structure defined on

$$\Gamma / \{\text{integral manifold of } \text{Ker}(\omega)\}.$$

# (Pre)–Symplectic structure

- If  $V$  is bounded by two Cauchy surfaces  $\Sigma$  and  $\Sigma'$  connected by some region  $\mathcal{K}_\infty \subset i^0$ , a variation  $d\mathcal{S}_V$  around a solution is

$$i^*d\mathcal{S}_V = \theta_{\Sigma'} - \theta_\Sigma + \theta_{\mathcal{K}_\infty}, \quad i : \Gamma \rightarrow \mathcal{F}.$$

- Taking the exterior derivative, we get

$$0 = i^*d^2\mathcal{S}_V = d(i^*d\mathcal{S}_V) = \omega_{\Sigma'} - \omega_\Sigma + \omega_{\mathcal{K}_\infty}.$$

- Choosing boundary conditions such that  $\omega_{\mathcal{K}_\infty} = 0$ ,  $\omega$  is independent of the Cauchy surface.
- In general,  $\omega$  is degenerate. If  $X, X' \in \text{Ker}(\omega)$ ,

$$\begin{aligned} 0 &= \mathcal{L}_{X'}\omega(X, Y) = \omega(\mathcal{L}_{X'}X, Y) + \omega(X, \mathcal{L}_{X'}Y) \\ &= \omega([X', X], Y). \end{aligned}$$

so  $\text{Ker}(\omega)$  is integrable and one can quotient  $\Gamma$  by the integral manifolds of  $\text{Ker}(\omega)$  and obtain a non-degenerate symplectic structure defined on

$$\Gamma / \{\text{integral manifold of } \text{Ker}(\omega)\}.$$

# (Pre)–Symplectic structure

- If  $V$  is bounded by two Cauchy surfaces  $\Sigma$  and  $\Sigma'$  connected by some region  $\mathcal{K}_\infty \subset i^0$ , a variation  $d\mathcal{S}_V$  around a solution is

$$i^*d\mathcal{S}_V = \theta_{\Sigma'} - \theta_\Sigma + \theta_{\mathcal{K}_\infty}, \quad i : \Gamma \rightarrow \mathcal{F}.$$

- Taking the exterior derivative, we get

$$0 = i^*d^2\mathcal{S}_V = d(i^*d\mathcal{S}_V) = \omega_{\Sigma'} - \omega_\Sigma + \omega_{\mathcal{K}_\infty}.$$

- Choosing boundary conditions such that  $\omega_{\mathcal{K}_\infty} = 0$ ,  $\omega$  is independent of the Cauchy surface.
- In general,  $\omega$  is degenerate. If  $X, X' \in \text{Ker}(\omega)$ ,

$$\begin{aligned} 0 &= \mathcal{L}_{X'}\omega(X, Y) = \omega(\mathcal{L}_{X'}X, Y) + \omega(X, \mathcal{L}_{X'}Y) \\ &= \omega([X', X], Y). \end{aligned}$$

so  $\text{Ker}(\omega)$  is integrable and one can quotient  $\Gamma$  by the integral manifolds of  $\text{Ker}(\omega)$  and obtain a non-degenerate symplectic structure defined on

$$\Gamma / \{\text{integral manifold of } \text{Ker}(\omega)\}.$$

# (Pre)–Symplectic structure

- If  $V$  is bounded by two Cauchy surfaces  $\Sigma$  and  $\Sigma'$  connected by some region  $\mathcal{K}_\infty \subset i^0$ , a variation  $d\mathcal{S}_V$  around a solution is

$$i^*d\mathcal{S}_V = \theta_{\Sigma'} - \theta_\Sigma + \theta_{\mathcal{K}_\infty}, \quad i : \Gamma \rightarrow \mathcal{F}.$$

- Taking the exterior derivative, we get

$$0 = i^*d^2\mathcal{S}_V = d(i^*d\mathcal{S}_V) = \omega_{\Sigma'} - \omega_\Sigma + \omega_{\mathcal{K}_\infty}.$$

- Choosing boundary conditions such that  $\omega_{\mathcal{K}_\infty} = 0$ ,  $\omega$  is independent of the Cauchy surface.
- In general,  $\omega$  is degenerate. If  $X, X' \in \text{Ker}(\omega)$ ,

$$\begin{aligned} 0 &= \mathcal{L}_{X'}\omega(X, Y) = \omega(\mathcal{L}_{X'}X, Y) + \omega(X, \mathcal{L}_{X'}Y) \\ &= \omega([X', X], Y). \end{aligned}$$

so  $\text{Ker}(\omega)$  is integrable and one can quotient  $\Gamma$  by the integral manifolds of  $\text{Ker}(\omega)$  and obtain a non-degenerate symplectic structure defined on

$$\Gamma / \{\text{integral manifold of } \text{Ker}(\omega)\}.$$



# (Pre)–Symplectic structure

- If  $\mathcal{S}_V$  is of first order,

$$\theta_\Sigma(X) = \int_\Sigma \frac{\partial \mathcal{L}}{\partial \nabla_a \phi^\alpha} X^\alpha dS_a,$$

# (Pre)–Symplectic structure

- If  $\mathcal{S}_V$  is of **first order**,

$$\theta_\Sigma(X) = \int_\Sigma \underbrace{\frac{\partial \mathcal{L}}{\partial \nabla_a \phi^\alpha} X^\alpha}_{p \, dq} dS_a,$$

$$\omega(X, Y) = \int_\Sigma (\mathcal{J}_1^a + \mathcal{J}_2^a) dS_a,$$

$$\mathcal{J}_1^a := \frac{\partial^2 \mathcal{L}}{\partial \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha X^\beta - X^\alpha Y^\beta),$$

$$\mathcal{J}_2^a = \frac{\partial^2 \mathcal{L}}{\partial \nabla_b \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha \nabla_b X^\beta - X^\alpha \nabla_b Y^\beta).$$

- By virtue of **field equations**,

$$\nabla_a (\mathcal{J}_1^a + \mathcal{J}_2^a) = 0.$$

# (Pre)–Symplectic structure

- If  $\mathcal{S}_V$  is of **first order**,

$$\theta_\Sigma(X) = \int_\Sigma \underbrace{\frac{\partial \mathcal{L}}{\partial \nabla_a \phi^\alpha} X^\alpha}_{p \, dq} \, dS_a,$$

$$\omega(X, Y) = \int_\Sigma (\mathcal{J}_1^a + \mathcal{J}_2^a) \, dS_a,$$

$$\mathcal{J}_1^a := \frac{\partial^2 \mathcal{L}}{\partial \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha X^\beta - X^\alpha Y^\beta),$$

$$\mathcal{J}_2^a = \frac{\partial^2 \mathcal{L}}{\partial \nabla_b \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha \nabla_b X^\beta - X^\alpha \nabla_b Y^\beta).$$

- By virtue of **field equations**,

$$\nabla_a (\mathcal{J}_1^a + \mathcal{J}_2^a) = 0.$$

# (Pre)–Symplectic structure

- If  $\mathcal{S}_V$  is of **first order**,

$$\theta_{\Sigma}(X) = \int_{\Sigma} \underbrace{\frac{\partial \mathcal{L}}{\partial \nabla_a \phi^\alpha} X^\alpha}_{p \, dq} dS_a,$$

$$\omega(X, Y) = \int_{\Sigma} (\mathcal{J}_1^a + \mathcal{J}_2^a) dS_a,$$

$$\mathcal{J}_1^a := \frac{\partial^2 \mathcal{L}}{\partial \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha X^\beta - X^\alpha Y^\beta),$$

$$\mathcal{J}_2^a = \frac{\partial^2 \mathcal{L}}{\partial \nabla_b \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha \nabla_b X^\beta - X^\alpha \nabla_b Y^\beta).$$

- By virtue of **field equations**,

$$\nabla_a (\mathcal{J}_1^a + \mathcal{J}_2^a) = 0.$$

- If  $\mathcal{S}_V$  is of **first order**,

$$\theta_\Sigma(X) = \int_\Sigma \underbrace{\frac{\partial \mathcal{L}}{\partial \nabla_a \phi^\alpha} X^\alpha}_{p \, dq} dS_a,$$

$$\omega(X, Y) = \int_\Sigma (\mathcal{J}_1^a + \mathcal{J}_2^a) dS_a,$$

$$\mathcal{J}_1^a := \frac{\partial^2 \mathcal{L}}{\partial \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha X^\beta - X^\alpha Y^\beta),$$

$$\mathcal{J}_2^a = \frac{\partial^2 \mathcal{L}}{\partial \nabla_b \phi^\beta \partial \nabla_a \phi^\alpha} (Y^\alpha \nabla_b X^\beta - X^\alpha \nabla_b Y^\beta).$$

- By virtue of **field equations**,

$$\nabla_a (\mathcal{J}_1^a + \mathcal{J}_2^a) = 0.$$

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.



# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# Symmetries and conserved quantities

- A smooth vector field on  $\Gamma$ ,  $\xi : \Gamma \rightarrow T\Gamma$  is called an **infinitesimal canonical transformation** if

$$\mathcal{L}_\xi \omega = 0$$

- Is there some *conserved quantity* associated with  $\xi$ ?

$$\mathcal{L}_\xi \omega = (d\omega)(\xi, \cdot, \cdot) + d(\omega(\xi, \cdot)) = d(\omega(\xi, \cdot)),$$

Thus, if  $\xi$  is an infinitesimal canonical transf., there exists a **locally closed one form**

$$\theta_\xi(X) := \omega(\xi, X).$$

- Thus, there also exists a scalar function (the **conserved quantity**)  $\mathcal{C}_\xi$  such that

$$d\mathcal{C}_\xi = \theta_\xi.$$

- If  $\xi \in \text{Ker}(\omega)$ , then  $\xi$  is an infinitesimal symmetry.

# PART III

## Scalar Electrodynamics

# Scalar Electrodynamics (SED)

- Consider a complex scalar field  $\Phi$  with mass  $m$  and charge  $e$ , and a Maxwell field  $F_{ab} := 2\partial_{[a}A_{b]}$  in  $\mathcal{M}$ .
- The Lagrangian of the theory takes the form

$$\mathcal{L}(\Phi, A_a) = (\mathcal{D}_a\Phi)(\mathcal{D}^a\Phi)^* - m^2|\Phi|^2 - \frac{1}{4}F_{ab}F^{ab},$$

where

$$\mathcal{D}_a\Phi = (\nabla_a + ieA_a)\Phi, \quad (\mathcal{D}^a\Phi)^* = (\nabla^a - ieA^a)\Phi^*.$$

- $\mathcal{L}$  is invariant under

$$\begin{pmatrix} \Phi \\ A_a \end{pmatrix} \mapsto \begin{pmatrix} e^{-ie\lambda}\Phi \\ A_a + \nabla_a\lambda \end{pmatrix}, \quad \lambda: \mathcal{M} \rightarrow \mathbb{R}.$$

# Scalar Electrodynamics (SED)

- Consider a complex scalar field  $\Phi$  with mass  $m$  and charge  $e$ , and a Maxwell field  $F_{ab} := 2\partial_{[a}A_{b]}$  in  $\mathcal{M}$ .
- The **Lagrangian** of the theory takes the form

$$\mathcal{L}(\Phi, A_a) = (\mathcal{D}_a\Phi)(\mathcal{D}^a\Phi)^* - m^2|\Phi|^2 - \frac{1}{4}F_{ab}F^{ab},$$

where

$$\mathcal{D}_a\Phi = (\nabla_a + ieA_a)\Phi, \quad (\mathcal{D}^a\Phi)^* = (\nabla^a - ieA^a)\Phi^*.$$

- $\mathcal{L}$  is **invariant** under

$$\begin{pmatrix} \Phi \\ A_a \end{pmatrix} \mapsto \begin{pmatrix} e^{-ie\lambda}\Phi \\ A_a + \nabla_a\lambda \end{pmatrix}, \quad \lambda: \mathcal{M} \rightarrow \mathbb{R}.$$

# Scalar Electrodynamics (SED)

- Consider a complex scalar field  $\Phi$  with mass  $m$  and charge  $e$ , and a Maxwell field  $F_{ab} := 2\partial_{[a}A_{b]}$  in  $\mathcal{M}$ .
- The **Lagrangian** of the theory takes the form

$$\mathcal{L}(\Phi, A_a) = (\mathcal{D}_a\Phi)(\mathcal{D}^a\Phi)^* - m^2|\Phi|^2 - \frac{1}{4}F_{ab}F^{ab},$$

where

$$\mathcal{D}_a\Phi = (\nabla_a + ieA_a)\Phi, \quad (\mathcal{D}^a\Phi)^* = (\nabla^a - ieA^a)\Phi^*.$$

- $\mathcal{L}$  is **invariant** under

$$\begin{pmatrix} \Phi \\ A_a \end{pmatrix} \mapsto \begin{pmatrix} e^{-ie\lambda}\Phi \\ A_a + \nabla_a\lambda \end{pmatrix}, \quad \lambda: \mathcal{M} \rightarrow \mathbb{R}.$$



# Scalar Electrodynamics (SED)

- Consider a complex scalar field  $\Phi$  with mass  $m$  and charge  $e$ , and a Maxwell field  $F_{ab} := 2\partial_{[a}A_{b]}$  in  $\mathcal{M}$ .
- The **Lagrangian** of the theory takes the form

$$\mathcal{L}(\Phi, A_a) = (\mathcal{D}_a\Phi)(\mathcal{D}^a\Phi)^* - m^2|\Phi|^2 - \frac{1}{4}F_{ab}F^{ab},$$

where

$$\mathcal{D}_a\Phi = (\nabla_a + ieA_a)\Phi, \quad (\mathcal{D}^a\Phi)^* = (\nabla^a - ieA^a)\Phi^*.$$

- $\mathcal{L}$  is **invariant** under

$$\begin{pmatrix} \Phi \\ A_a \end{pmatrix} \mapsto \begin{pmatrix} e^{-ie\lambda}\Phi \\ A_a + \nabla_a\lambda \end{pmatrix}, \quad \lambda: \mathcal{M} \rightarrow \mathbb{R}.$$

# Field equations and Symplectic structure

- **Field Equations:**

$$\square\Phi + [m^2 - e^2 A^a A_a + ie\nabla_a A^a + 2ieA^a\nabla_a]\Phi = 0,$$

$$\nabla_c\nabla^d A^c - \square A^d = ie[\Phi\nabla^a\Phi^* - \Phi^*\nabla^a\Phi] + 2e^2\Phi\Phi^*A^a.$$

- The **covariant phase space** is, thus,

$$\Gamma = \{\phi^\alpha := (\Phi, A_a) | \Phi \text{ and } A_a \text{ satisfy field eq.}\}.$$

- Since the action  $\mathcal{S} = \int \sqrt{-g} d^4x \mathcal{L}$  is of **first order**, the **symplectic structure** takes the form

$$\omega(X, Y) = \int_\Sigma \mathcal{J}_1^a(X, Y) dS_a + \int_\Sigma \mathcal{J}_2^a(X, Y) dS_a,$$

where  $\Sigma$  is any Cauchy surface in  $\mathcal{M}$  with boundary  $\partial\Sigma$ .

# Field equations and Symplectic structure

- **Field Equations:**

$$\square\Phi + [m^2 - e^2 A^a A_a + ie\nabla_a A^a + 2ieA^a\nabla_a]\Phi = 0,$$

$$\nabla_c\nabla^d A^c - \square A^d = ie[\Phi\nabla^a\Phi^* - \Phi^*\nabla^a\Phi] + 2e^2\Phi\Phi^*A^a.$$

- The **covariant phase space** is, thus,

$$\Gamma = \{\phi^\alpha := (\Phi, A_a) | \Phi \text{ and } A_a \text{ satisfy field eq.}\}.$$

- Since the action  $\mathcal{S} = \int \sqrt{-g} d^4x \mathcal{L}$  is of **first order**, the **symplectic structure** takes the form

$$\omega(X, Y) = \int_\Sigma \mathcal{J}_1^a(X, Y) dS_a + \int_\Sigma \mathcal{J}_2^a(X, Y) dS_a,$$

where  $\Sigma$  is any Cauchy surface in  $\mathcal{M}$  with boundary  $\partial\Sigma$ .

# Field equations and Symplectic structure

- **Field Equations:**

$$\square\Phi + [m^2 - e^2 A^a A_a + ie\nabla_a A^a + 2ieA^a\nabla_a]\Phi = 0,$$

$$\nabla_c\nabla^d A^c - \square A^d = ie[\Phi\nabla^a\Phi^* - \Phi^*\nabla^a\Phi] + 2e^2\Phi\Phi^* A^a.$$

- The **covariant phase space** is, thus,

$$\Gamma = \{\phi^\alpha := (\Phi, A_a) | \Phi \text{ and } A_a \text{ satisfy field eq.}\}.$$

- Since the action  $\mathcal{S} = \int \sqrt{-g} d^4x \mathcal{L}$  is of **first order**, the **symplectic structure** takes the form

$$\omega(X, Y) = \int_\Sigma \mathcal{J}_1^a(X, Y) dS_a + \int_\Sigma \mathcal{J}_2^a(X, Y) dS_a,$$

where  $\Sigma$  is any Cauchy surface in  $\mathcal{M}$  with boundary  $\partial\Sigma$ .

# Field equations and Symplectic structure

- $X$  and  $Y$  are solutions to **linearized field equations** around some solution  $\phi^\alpha$ :

$$X^\alpha = \delta\phi^\alpha = (\delta\Phi, \delta A_a) := (\Psi, \alpha_a).$$

- Let's take  $X = (\Psi_1, \alpha_1^a)$  and  $Y = (\Psi_2, \alpha_2^a)$ . The currents of  $\omega$  are

$$\begin{aligned} \mathcal{J}_1^a(X, Y) = & 2ieA^a (\Psi_1\Psi_2^* - \Psi_2\Psi_1^*) + ie\Phi (\Psi_2^*\alpha_1^a - \Psi_1^*\alpha_2^a) \\ & - ie\Phi^* (\Psi_2\alpha_1^a - \Psi_1\alpha_2^a), \end{aligned}$$

and

$$\begin{aligned} \mathcal{J}_2^a(X, Y) = & \Psi_2\nabla^a\Psi_1^* - \Psi_1\nabla^a\Psi_2^* + \Psi_2^*\nabla^a\Psi_1 - \Psi_1^*\nabla^a\Psi_2 + \alpha_2^b\nabla_b\alpha_1^a \\ & - \alpha_1^b\nabla_b\alpha_2^a - \alpha_2^b\nabla^a\alpha_b^1 + \alpha_1^b\nabla^a\alpha_b^2. \end{aligned}$$

# Field equations and Symplectic structure

- $X$  and  $Y$  are solutions to **linearized field equations** around some solution  $\phi^\alpha$ :

$$X^\alpha = \delta\phi^\alpha = (\delta\Phi, \delta A_a) := (\Psi, \alpha_a).$$

- Let's take  $X = (\Psi_1, \alpha_a^1)$  and  $Y = (\Psi_2, \alpha_a^2)$ . The currents of  $\omega$  are

$$\begin{aligned} \mathcal{J}_1^a(X, Y) &= 2ieA^a (\Psi_1\Psi_2^* - \Psi_2\Psi_1^*) + ie\Phi (\Psi_2^*\alpha_1^a - \Phi_1^*\alpha_2^a) \\ &\quad - ie\Phi^* (\Psi_2\alpha_1^a - \Psi_1\alpha_2^a), \end{aligned}$$

and

$$\begin{aligned} \mathcal{J}_2^a(X, Y) &= \Psi_2\nabla^a\Psi_1^* - \Psi_1\nabla^a\Psi_2^* + \Psi_2^*\nabla^a\Psi_1 - \Psi_1^*\nabla^a\Psi_2 + \alpha_2^b\nabla_b\alpha_1^a \\ &\quad - \alpha_1^b\nabla_b\alpha_2^a - \alpha_2^b\nabla^a\alpha_b^1 + \alpha_1^b\nabla^a\alpha_b^2. \end{aligned}$$

# Field equations and Symplectic structure

- $X$  and  $Y$  are solutions to **linearized field equations** around some solution  $\phi^\alpha$ :

$$X^\alpha = \delta\phi^\alpha = (\delta\Phi, \delta A_a) := (\Psi, \alpha_a).$$

- Let's take  $X = (\Psi_1, \alpha_a^1)$  and  $Y = (\Psi_2, \alpha_a^2)$ . The currents of  $\omega$  are

$$\begin{aligned} \mathcal{J}_1^a(X, Y) = & 2ieA^a (\Psi_1\Psi_2^* - \Psi_2\Psi_1^*) + ie\Phi (\Psi_2^*\alpha_1^a - \Phi_1^*\alpha_2^a) \\ & - ie\Phi^* (\Psi_2\alpha_1^a - \Psi_1\alpha_2^a), \end{aligned}$$

and

$$\begin{aligned} \mathcal{J}_2^a(X, Y) = & \Psi_2\nabla^a\Psi_1^* - \Psi_1\nabla^a\Psi_2^* + \Psi_2^*\nabla^a\Psi_1 - \Psi_1^*\nabla^a\Psi_2 + \alpha_2^b\nabla_b\alpha_1^a \\ & - \alpha_1^b\nabla_b\alpha_2^a - \alpha_2^b\nabla^a\alpha_b^1 + \alpha_1^b\nabla^a\alpha_b^2. \end{aligned}$$

# Linearized problem and infinitesimal gauge transformation

- Explicitly, the perturbations  $(\Psi, \alpha_a)$  satisfy

$$\begin{aligned} [\square + m^2 - e^2 A^a A_a + ie \nabla_a A^a + 2ie A^a \nabla_a] \Psi &= [2e^2 A^a \alpha_a \\ &\quad - ie \nabla_a \alpha^a - 2ie \alpha^a \nabla_a] \Phi; \end{aligned}$$

$$\begin{aligned} \nabla_b \nabla^a \alpha^b - \square \alpha^a &= ie [\Phi \nabla^a \Psi^* + \Psi \nabla^a \Phi^* - \Phi^* \nabla^a \Psi - \Psi^* \nabla^a \Phi] \\ &\quad + 2e^2 [\Phi \Phi^* \alpha^a + \Phi \Psi^* A^a + \Psi \Phi^* A^a]. \end{aligned}$$

- In particular, the infinitesimal gauge transformation

$$X_G := (-ie\lambda\Phi, \nabla_a \lambda),$$

satisfies the equations above trivially if we assume that  $\nabla_a$  is torsion free.



# Linearized problem and infinitesimal gauge transformation

- Explicitly, the perturbations  $(\Psi, \alpha_a)$  satisfy

$$\begin{aligned} [\square + m^2 - e^2 A^a A_a + ie \nabla_a A^a + 2ie A^a \nabla_a] \Psi &= [2e^2 A^a \alpha_a \\ &\quad - ie \nabla_a \alpha^a - 2ie \alpha^a \nabla_a] \Phi; \end{aligned}$$

$$\begin{aligned} \nabla_b \nabla^a \alpha^b - \square \alpha^a &= ie [\Phi \nabla^a \Psi^* + \Psi \nabla^a \Phi^* - \Phi^* \nabla^a \Psi - \Psi^* \nabla^a \Phi] \\ &\quad + 2e^2 [\Phi \Phi^* \alpha^a + \Phi \Psi^* A^a + \Psi \Phi^* A^a]. \end{aligned}$$

- In particular, the infinitesimal gauge transformation

$$X_G := (-ie\lambda\Phi, \nabla_a \lambda),$$

satisfies the equations above trivially if we assume that  $\nabla_a$  is torsion free.

# Linearized problem and infinitesimal gauge transformation

- Explicitly, the perturbations  $(\Psi, \alpha_a)$  satisfy

$$\begin{aligned} [\square + m^2 - e^2 A^a A_a + ie \nabla_a A^a + 2ie A^a \nabla_a] \Psi &= [2e^2 A^a \alpha_a \\ &\quad - ie \nabla_a \alpha^a - 2ie \alpha^a \nabla_a] \Phi; \end{aligned}$$

$$\begin{aligned} \nabla_b \nabla^a \alpha^b - \square \alpha^a &= ie [\Phi \nabla^a \Psi^* + \Psi \nabla^a \Phi^* - \Phi^* \nabla^a \Psi - \Psi^* \nabla^a \Phi] \\ &\quad + 2e^2 [\Phi \Phi^* \alpha^a + \Phi \Psi^* A^a + \Psi \Phi^* A^a]. \end{aligned}$$

- In particular, the **infinitesimal gauge transformation**

$$X_G := (-ie\lambda\Phi, \nabla_a\lambda),$$

satisfies the equations above trivially if we assume that  $\nabla_a$  is torsion free.

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?

**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \Rightarrow \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \Rightarrow \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .



- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \Rightarrow \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

- Computing  $\omega(X_G, Y)$  and integrating by parts, we obtain

$$\omega(X_G, Y) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} \alpha_{b]}^2 t^a n^b dS,$$

where the integral is over  $\Sigma$ , with time-like normal  $n^a$  and  $t^a$  is spacelike normal to  $\partial\Sigma$ . If  $\lambda \rightarrow 0$  at  $\partial\Sigma \subset i^0$ ,  $X_G \in \text{Ker}(\omega)$ .

- **Quiz:** Does  $\text{Ker}(\omega)$  include all local symmetries of the theory?  
**Answer:** No! Explicitly,

$$\mathcal{L}_{X_G} \omega = (d\omega)(X_G, \cdot, \cdot) + d(\omega(X_G, \cdot)) = 0.$$

- The conserved quantity  $\mathcal{C}_{X_G}$  is such that

$$d\mathcal{C}_{X_G}(Y) = \omega(X_G, Y) \quad \Rightarrow \quad \mathcal{C}_{X_G}(A) = 2 \oint_{\partial\Sigma} \lambda \nabla_{[a} A_{b]} t^a n^b dS,$$

that is, the **electromagnetic charge** when  $\lambda \rightarrow 1$ .

## Particular case: $m = 0$

- *What happens at null infinity?* We consider the conformal transformation

$$\tilde{g}_{ab} = \Omega^2 g_{ab}, \quad \Omega : \tilde{\mathcal{M}} \rightarrow \mathbb{R}, \quad \Omega > 0,$$

where  $\tilde{g}_{ab}$  represents the **physical** metric, and  $g_{ab}$  the **unphysical** one.

- $\Omega = 0$  represents **null infinity**,  $\mathcal{I}^\pm$ . Since  $F_{ab}$  is conformally invariant, it must be

$$\tilde{A}_a = A_a, \quad \tilde{A}^a = \Omega^{-2} A^a.$$

- Putting  $\tilde{\Phi} = \Omega^{-1} \Phi$ , the first field equation becomes

$$\square \Phi - e^2 A^a A_a \Phi + ie \Phi \nabla_a A^a + 2ie A^a \nabla_a \Phi = \\ \Omega^2 \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \tilde{\nabla}_b \Omega - 2\Omega \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \Omega \tilde{\nabla}_b \Omega.$$

## Particular case: $m = 0$

- *What happens at null infinity?* We consider the conformal transformation

$$\tilde{g}_{ab} = \Omega^2 g_{ab}, \quad \Omega : \tilde{\mathcal{M}} \rightarrow \mathbb{R}, \quad \Omega > 0,$$

where  $\tilde{g}_{ab}$  represents the **physical** metric, and  $g_{ab}$  the **unphysical** one.

- $\Omega = 0$  represents **null infinity**,  $\mathcal{I}^\pm$ . Since  $F_{ab}$  is conformally invariant, it must be

$$\tilde{A}_a = A_a, \quad \tilde{A}^a = \Omega^{-2} A^a.$$

- Putting  $\tilde{\Phi} = \Omega^{-1} \Phi$ , the first field equation becomes

$$\square \Phi - e^2 A^a A_a \Phi + ie \Phi \nabla_a A^a + 2ie A^a \nabla_a \Phi = \\ \Omega^2 \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \tilde{\nabla}_b \Omega - 2\Omega \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \Omega \tilde{\nabla}_b \Omega.$$

## Particular case: $m = 0$

- *What happens at null infinity?* We consider the conformal transformation

$$\tilde{g}_{ab} = \Omega^2 g_{ab}, \quad \Omega : \tilde{\mathcal{M}} \rightarrow \mathbb{R}, \quad \Omega > 0,$$

where  $\tilde{g}_{ab}$  represents the **physical** metric, and  $g_{ab}$  the **unphysical** one.

- $\Omega = 0$  represents **null infinity**,  $\mathcal{I}^\pm$ . Since  $F_{ab}$  is conformally invariant, it must be

$$\tilde{A}_a = A_a, \quad \tilde{A}^a = \Omega^{-2} A^a.$$

- Putting  $\tilde{\Phi} = \Omega^{-1} \Phi$ , the first field equation becomes

$$\square \Phi - e^2 A^a A_a \Phi + ie \Phi \nabla_a A^a + 2ie A^a \nabla_a \Phi = \\ \Omega^2 \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \tilde{\nabla}_b \Omega - 2\Omega \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \Omega \tilde{\nabla}_b \Omega.$$

## Particular case: $m = 0$

- *What happens at null infinity?* We consider the conformal transformation

$$\tilde{g}_{ab} = \Omega^2 g_{ab}, \quad \Omega : \tilde{\mathcal{M}} \rightarrow \mathbb{R}, \quad \Omega > 0,$$

where  $\tilde{g}_{ab}$  represents the **physical** metric, and  $g_{ab}$  the **unphysical** one.

- $\Omega = 0$  represents **null infinity**,  $\mathcal{I}^\pm$ . Since  $F_{ab}$  is conformally invariant, it must be

$$\tilde{A}_a = A_a, \quad \tilde{A}^a = \Omega^{-2} A^a.$$

- Putting  $\tilde{\Phi} = \Omega^{-1} \Phi$ , the first field equation becomes

$$\square \Phi - e^2 A^a A_a \Phi + ie \Phi \nabla_a A^a + 2ie A^a \nabla_a \Phi = \\ \Omega^2 \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \tilde{\nabla}_b \Omega - 2\Omega \tilde{\Phi} \tilde{g}^{ab} \tilde{\nabla}_a \Omega \tilde{\nabla}_b \Omega.$$

# How does $\tilde{\omega}(\tilde{X}, \tilde{Y})$ change?

- The volume element in the physical picture is

$$d\tilde{S}_a = \tilde{t}_a d\tilde{S} = \tilde{t}_a |\tilde{h}|^{1/2} d^3\tilde{x}, \quad \tilde{t}^a \tilde{t}_a = -1, \quad h_{ab} = g_{ab}|_{\Sigma}.$$

- Under the transformation  $\tilde{h}_{ab} = \Omega^2 h_{ab}$ , and taking  $t^a t_a = -1$ ,

$$\tilde{h} = \Omega^6 h \quad \Rightarrow \quad |\tilde{h}|^{1/2} = \Omega^3 |h|^{1/2};$$

$$\tilde{t}_a = \Omega t_a, \quad \Rightarrow \quad \boxed{d\tilde{S}_a = \Omega^4 dS_a}$$

- By direct calculation, it can be shown that

$$\boxed{\tilde{\mathcal{J}}_j^a(\tilde{X}, \tilde{Y}) = \Omega^{-4} \mathcal{J}_j^a(X, Y); \quad j = 1, 2.}$$

- Thus, if the integration is over **space-like** Cauchy surfaces, the symplectic structure results **conformally invariant**.

$$\boxed{\tilde{\omega}(\tilde{X}, \tilde{Y}) = \omega(X, Y)}$$



# How does $\tilde{\omega}(\tilde{X}, \tilde{Y})$ change?

- The volume element in the physical picture is

$$d\tilde{S}_a = \tilde{t}_a d\tilde{S} = \tilde{t}_a |\tilde{h}|^{1/2} d^3\tilde{x}, \quad \tilde{t}^a \tilde{t}_a = -1, \quad h_{ab} = g_{ab}|_{\Sigma}.$$

- Under the transformation  $\tilde{h}_{ab} = \Omega^2 h_{ab}$ , and taking  $t^a t_a = -1$ ,

$$\tilde{h} = \Omega^6 h \quad \Rightarrow \quad |\tilde{h}|^{1/2} = \Omega^3 |h|^{1/2};$$

$$\tilde{t}_a = \Omega t_a, \quad \Rightarrow \quad \boxed{d\tilde{S}_a = \Omega^4 dS_a}$$

- By direct calculation, it can be shown that

$$\boxed{\tilde{\mathcal{J}}_j^a(\tilde{X}, \tilde{Y}) = \Omega^{-4} \mathcal{J}_j^a(X, Y); \quad j = 1, 2.}$$

- Thus, if the integration is over **space-like** Cauchy surfaces, the symplectic structure results **conformally invariant**.

$$\boxed{\tilde{\omega}(\tilde{X}, \tilde{Y}) = \omega(X, Y)}$$

# How does $\tilde{\omega}(\tilde{X}, \tilde{Y})$ change?

- The volume element in the physical picture is

$$d\tilde{S}_a = \tilde{t}_a d\tilde{S} = \tilde{t}_a |\tilde{h}|^{1/2} d^3\tilde{x}, \quad \tilde{t}^a \tilde{t}_a = -1, \quad h_{ab} = g_{ab}|_{\Sigma}.$$

- Under the transformation  $\tilde{h}_{ab} = \Omega^2 h_{ab}$ , and taking  $t^a t_a = -1$ ,

$$\tilde{h} = \Omega^6 h \quad \Rightarrow \quad |\tilde{h}|^{1/2} = \Omega^3 |h|^{1/2};$$

$$\tilde{t}_a = \Omega t_a, \quad \Rightarrow \quad \boxed{d\tilde{S}_a = \Omega^4 dS_a}$$

- By direct calculation, it can be shown that

$$\boxed{\tilde{\mathcal{J}}_j^a(\tilde{X}, \tilde{Y}) = \Omega^{-4} \mathcal{J}_j^a(X, Y); \quad j = 1, 2.}$$

- Thus, if the integration is over **space-like** Cauchy surfaces, the symplectic structure results **conformally invariant**.

$$\boxed{\tilde{\omega}(\tilde{X}, \tilde{Y}) = \omega(X, Y)}$$

# How does $\tilde{\omega}(\tilde{X}, \tilde{Y})$ change?

- The volume element in the physical picture is

$$d\tilde{S}_a = \tilde{t}_a d\tilde{S} = \tilde{t}_a |\tilde{h}|^{1/2} d^3\tilde{x}, \quad \tilde{t}^a \tilde{t}_a = -1, \quad h_{ab} = g_{ab}|_{\Sigma}.$$

- Under the transformation  $\tilde{h}_{ab} = \Omega^2 h_{ab}$ , and taking  $t^a t_a = -1$ ,

$$\tilde{h} = \Omega^6 h \quad \Rightarrow \quad |\tilde{h}|^{1/2} = \Omega^3 |h|^{1/2};$$

$$\tilde{t}_a = \Omega t_a, \quad \Rightarrow \quad \boxed{d\tilde{S}_a = \Omega^4 dS_a}$$

- By direct calculation, it can be shown that

$$\boxed{\tilde{\mathcal{J}}_j^a(\tilde{X}, \tilde{Y}) = \Omega^{-4} \mathcal{J}_j^a(X, Y); \quad j = 1, 2.}$$

- Thus, if the integration is over space-like Cauchy surfaces, the symplectic structure results **conformally invariant**.

$$\boxed{\tilde{\omega}(\tilde{X}, \tilde{Y}) = \omega(X, Y)}$$

# How does $\tilde{\omega}(\tilde{X}, \tilde{Y})$ change?

- The volume element in the physical picture is

$$d\tilde{S}_a = \tilde{t}_a d\tilde{S} = \tilde{t}_a |\tilde{h}|^{1/2} d^3\tilde{x}, \quad \tilde{t}^a \tilde{t}_a = -1, \quad h_{ab} = g_{ab}|_{\Sigma}.$$

- Under the transformation  $\tilde{h}_{ab} = \Omega^2 h_{ab}$ , and taking  $t^a t_a = -1$ ,

$$\tilde{h} = \Omega^6 h \quad \Rightarrow \quad |\tilde{h}|^{1/2} = \Omega^3 |h|^{1/2};$$

$$\tilde{t}_a = \Omega t_a, \quad \Rightarrow \quad \boxed{d\tilde{S}_a = \Omega^4 dS_a}$$

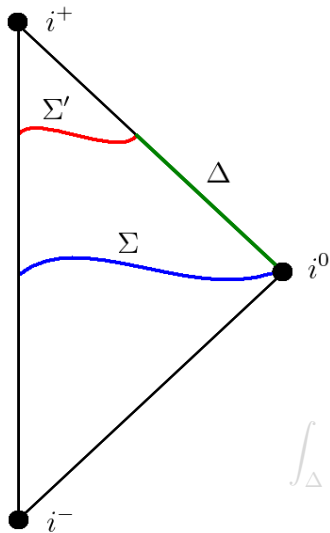
- By direct calculation, it can be shown that

$$\boxed{\tilde{\mathcal{J}}_j^a(\tilde{X}, \tilde{Y}) = \Omega^{-4} \mathcal{J}_j^a(X, Y); \quad j = 1, 2.}$$

- Thus, if the integration is over **space-like** Cauchy surfaces, the symplectic structure results **conformally invariant**.

$$\boxed{\tilde{\omega}(\tilde{X}, \tilde{Y}) = \omega(X, Y)}$$

# Conformal Symplectic structure



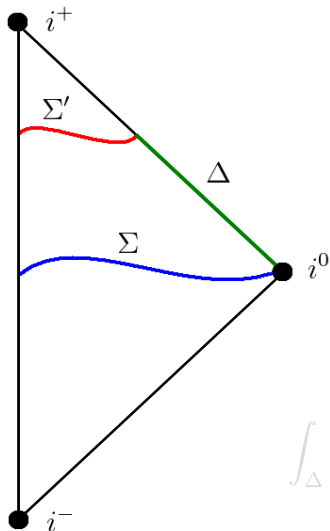
- $\omega$  does not depend on the Cauchy surface. In particular, one can take

$$\Sigma^* := \Sigma' \cup \Delta, \quad \Delta := S^2 \times I, \quad I \subset \mathbb{R}.$$

- $\nabla^a \mathcal{J}_a = 0$  on  $\mathcal{M}$ .
- Charge flux:**

$$\int_{\Delta} \mathcal{J}^a(X_G, Y) dS_a = dQ|_{i^0}(Y) - dQ|_C(Y)$$

# Conformal Symplectic structure



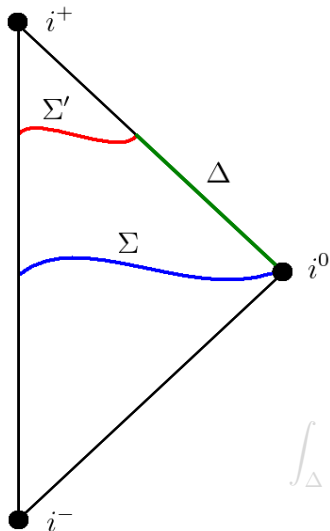
- $\omega$  does not depend on the Cauchy surface. In particular, one can take

$$\Sigma^* := \Sigma' \cup \Delta, \quad \Delta := S^2 \times I, \quad I \subset \mathbb{R}.$$

- $\nabla^a \mathcal{J}_a = 0$  on  $\mathcal{M}$ .
- **Charge flux:**

$$\int_{\Delta} \mathcal{J}^a(X_G, Y) dS_a = dQ|_{i^0}(Y) - dQ|_c(Y)$$

# Conformal Symplectic structure



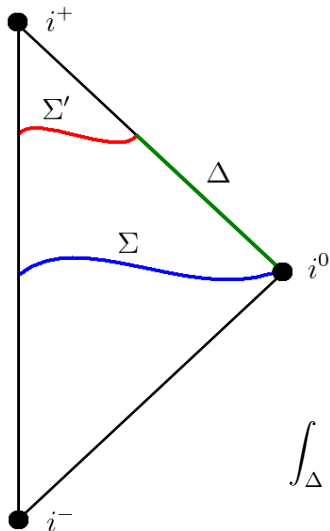
- $\omega$  does not depend on the Cauchy surface. In particular, one can take

$$\Sigma^* := \Sigma' \cup \Delta, \quad \Delta := S^2 \times I, \quad I \subset \mathbb{R}.$$

- $\nabla^a \mathcal{J}_a = 0$  on  $\mathcal{M}$ .
- **Charge flux:**

$$\int_{\Delta} \mathcal{J}^a(X_G, Y) dS_a = dQ|_{i^0}(Y) - dQ|_c(Y)$$

# Conformal Symplectic structure



- $\omega$  does not depend on the Cauchy surface. In particular, one can take

$$\Sigma^* := \Sigma' \cup \Delta, \quad \Delta := S^2 \times I, \quad I \subset \mathbb{R}.$$

- $\nabla^a \mathcal{J}_a = 0$  on  $\mathcal{M}$ .
- **Charge flux:**

$$\int_{\Delta} \mathcal{J}^a(X_G, Y) dS_a = dQ|_{i^0}(Y) - dQ|_C(Y)$$



# Global Symetries

- Let  $k^a$  be a **Killing vector field** in the spacetime background  $(\mathcal{M}, g_{ab})$ . Then,

$$\mathcal{L}_k g_{ab} = 0.$$

- If  $(\Phi, A_a) \in \Gamma$ , the perturbation

$$X^\alpha = (\dot{\Phi}, \dot{A}_a) := (\mathcal{L}_k \Phi, \mathcal{L}_k A_a)$$

satisfies the linearized SED equations, using the fact that  $\mathcal{L}$  conmmutes with  $\nabla_a$  along the Killing field.

- $\mathcal{L}_X \omega = 0 \Rightarrow$   **$X$  is a symmetry.**
- The **conserved quantity**  $\mathcal{C}$  associated with this symmetry is such that

$$d\mathcal{C}(\Psi, \alpha) = \int_{\Sigma} \left[ 2e \operatorname{Im} \left\{ 2\Psi \dot{\Phi}^* A^a - 2\dot{\Phi} \Psi^* A^a + \Phi \dot{\Phi}^* \alpha^a - \Phi \Psi^* \dot{A}^a \right\} + 2 \operatorname{Re} \left\{ \Psi \nabla^a \dot{\Phi}^* - \dot{\Phi} \nabla^a \Psi^* \right\} + \left[ \alpha, \dot{A} \right]^a + \dot{A}^b \nabla^a \alpha_b - \alpha^b \nabla^a \dot{A}_b \right] dS_a.$$

# Global Symetries

- Let  $k^a$  be a **Killing vector field** in the spacetime background  $(\mathcal{M}, g_{ab})$ . Then,

$$\mathcal{L}_k g_{ab} = 0.$$

- If  $(\Phi, A_a) \in \Gamma$ , the perturbation

$$X^\alpha = (\dot{\Phi}, \dot{A}_a) := (\mathcal{L}_k \Phi, \mathcal{L}_k A_a)$$

satisfies the **linearized SED equations**, using the fact that  $\mathcal{L}$  conmmutes with  $\nabla_a$  along the Killing field.

- $\mathcal{L}_X \omega = 0 \Rightarrow$   **$X$  is a symmetry.**
- The **conserved quantity**  $\mathcal{C}$  associated with this symmetry is such that

$$d\mathcal{C}(\Psi, \alpha) = \int_{\Sigma} \left[ 2e \operatorname{Im} \left\{ 2\Psi \dot{\Phi}^* A^a - 2\dot{\Phi} \Psi^* A^a + \Phi \dot{\Phi}^* \alpha^a - \Phi \Psi^* \dot{A}^a \right\} + \right. \\ \left. + 2 \operatorname{Re} \left\{ \Psi \nabla^a \dot{\Phi}^* - \dot{\Phi} \nabla^a \Psi^* \right\} + \left[ \alpha, \dot{A} \right]^a + \dot{A}^b \nabla^a \alpha_b - \alpha^b \nabla^a \dot{A}_b \right] dS_a.$$

# Global Symetries

- Let  $k^a$  be a **Killing vector field** in the spacetime background  $(\mathcal{M}, g_{ab})$ . Then,

$$\mathcal{L}_k g_{ab} = 0.$$

- If  $(\Phi, A_a) \in \Gamma$ , the perturbation

$$X^\alpha = (\dot{\Phi}, \dot{A}_a) := (\mathcal{L}_k \Phi, \mathcal{L}_k A_a)$$

satisfies the **linearized SED equations**, using the fact that  $\mathcal{L}$  conmmutes with  $\nabla_a$  along the Killing field.

- $\mathcal{L}_X \omega = 0 \Rightarrow$   **$X$  is a symmetry.**
- The **conserved quantity  $\mathcal{C}$**  associated with this symmetry is such that

$$d\mathcal{C}(\Psi, \alpha) = \int_{\Sigma} \left[ 2e \operatorname{Im} \left\{ 2\Psi\dot{\Phi}^* A^a - 2\dot{\Phi}\Psi^* A^a + \Phi\dot{\Phi}^* \alpha^a - \Phi\Psi^* \dot{A}^a \right\} + 2 \operatorname{Re} \left\{ \Psi\nabla^a \dot{\Phi}^* - \dot{\Phi}\nabla^a \Psi^* \right\} + \left[ \alpha, \dot{A} \right]^a + \dot{A}^b \nabla^a \alpha_b - \alpha^b \nabla^a \dot{A}_b \right] dS_a.$$

# Global Symetries

- Let  $k^a$  be a **Killing vector field** in the spacetime background  $(\mathcal{M}, g_{ab})$ . Then,

$$\mathcal{L}_k g_{ab} = 0.$$

- If  $(\Phi, A_a) \in \Gamma$ , the perturbation

$$X^\alpha = (\dot{\Phi}, \dot{A}_a) := (\mathcal{L}_k \Phi, \mathcal{L}_k A_a)$$

satisfies the **linearized SED equations**, using the fact that  $\mathcal{L}$  conmmutes with  $\nabla_a$  along the Killing field.

- $\mathcal{L}_X \omega = 0 \Rightarrow$   **$X$  is a symmetry.**
- The **conserved quantity**  $\mathcal{C}$  associated with this symmetry is such that

$$d\mathcal{C}(\Psi, \alpha) = \int_{\Sigma} \left[ 2e \operatorname{Im} \left\{ 2\Psi \dot{\Phi}^* A^a - 2\dot{\Phi} \Psi^* A^a + \Phi \dot{\Phi}^* \alpha^a - \Phi \Psi^* \dot{A}^a \right\} + 2 \operatorname{Re} \left\{ \Psi \nabla^a \dot{\Phi}^* - \dot{\Phi} \nabla^a \Psi^* \right\} + \left[ \alpha, \dot{A} \right]^a + \dot{A}^b \nabla^a \alpha_b - \alpha^b \nabla^a \dot{A}_b \right] dS_a.$$

# Global Symetries

- Let  $k^a$  be a **Killing vector field** in the spacetime background  $(\mathcal{M}, g_{ab})$ . Then,

$$\mathcal{L}_k g_{ab} = 0.$$

- If  $(\Phi, A_a) \in \Gamma$ , the perturbation

$$X^\alpha = (\dot{\Phi}, \dot{A}_a) := (\mathcal{L}_k \Phi, \mathcal{L}_k A_a)$$

satisfies the **linearized SED equations**, using the fact that  $\mathcal{L}$  conmmutes with  $\nabla_a$  along the Killing field.

- $\mathcal{L}_X \omega = 0 \Rightarrow$   **$X$  is a symmetry.**
- The **conserved quantity**  $\mathcal{C}$  associated with this symmetry is such that

$$\begin{aligned} d\mathcal{C}(\Psi, \alpha) = & \int_{\Sigma} \left[ 2e \operatorname{Im} \left\{ 2\Psi\dot{\Phi}^* A^a - 2\dot{\Phi}\Psi^* A^a + \Phi\dot{\Phi}^* \alpha^a - \Phi\Psi^* \dot{A}^a \right\} + \right. \\ & \left. + 2 \operatorname{Re} \left\{ \Psi\nabla^a \dot{\Phi}^* - \dot{\Phi}\nabla^a \Psi^* \right\} + \left[ \alpha, \dot{A} \right]^a + \dot{A}^b \nabla^a \alpha_b - \alpha^b \nabla^a \dot{A}_b \right] dS_a. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2 \nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} [\nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2] d^3x \\ &= - \int_{t=t_0} [\dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2 \nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} [\nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2] d^3x \\ &= - \int_{t=t_0} [\dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2 \nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} [\nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2] d^3x \\ &= - \int_{t=t_0} [\dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2] d^3x. \end{aligned}$$



# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2 \nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} [\nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2] d^3x \\ &= - \int_{t=t_0} [\dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2\nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} [\nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2] d^3x \\ &= - \int_{t=t_0} [\dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2\nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b d^3x = \int_{\Sigma} \left[ \nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2 \right] d^3x \\ &= - \int_{t=t_0} \left[ \dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2 \right] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- Setting  $F_{ab} = 0$  and  $\Phi = \Phi^*$ ,

$$\mathcal{L} = \nabla^a \Phi \nabla_a \Phi - m^2 \Phi^2, \quad \square \Phi + m^2 \Phi = 0, \quad (+, -, -, -).$$

- The energy-momentum tensor associated with  $\mathcal{L}$  is

$$T_{ab} = 2\nabla_a \Phi \nabla_b \Phi - g_{ab} (\nabla^c \Phi \nabla_c \Phi - m^2 \Phi^2).$$

- Taking  $(t, \vec{x})$  coordinates such that  $k^a = (\partial_t)^a$  with  $k^a k_a = 1$ , the energy over a  $t = t_0$  space-like slice,  $\Sigma$ , is

$$\begin{aligned} \mathcal{E}(\Phi) &= - \int_{\Sigma} T_{ab} k^a k^b \, d^3x = \int_{\Sigma} \left[ \nabla^c \Phi \nabla_c \Phi - 2\dot{\Phi}^2 - m^2 \Phi^2 \right] d^3x \\ &= - \int_{t=t_0} \left[ \dot{\Phi}^2 + |\vec{\nabla} \Phi|^2 + m^2 \Phi^2 \right] d^3x. \end{aligned}$$

# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} - \underbrace{\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \underbrace{-\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \underbrace{-\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} - \underbrace{\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$



# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \underbrace{-\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

# Example: Klein Gordon Equation

- The differential of energy is

$$\begin{aligned}d\mathcal{E}(\Psi) &= \left. \frac{d\mathcal{E}(\Phi + s\Psi)}{ds} \right|_{s=0} = -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \vec{\nabla}\Phi \cdot \vec{\nabla}\Psi + m^2\Phi\Psi \right] d^3x \\ &= -2 \int_{\Sigma} \left[ \dot{\Phi}\dot{\Psi} + \underbrace{-\Psi\nabla^2\Phi + m^2\Phi\Psi}_{=-\Psi\ddot{\Phi}} \right] d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

- Using the **symplectic formalism**,

$$\begin{aligned}d\mathcal{E}(\Psi) &= \omega(\dot{\Phi}, \Psi) = 2 \int_{\Sigma} \left[ \Psi\nabla^a\dot{\Phi} - \dot{\Phi}\nabla^a\Psi \right] k_a d^3x \\ &= 2 \int_{\Sigma} \left[ \Psi\ddot{\Phi} - \dot{\Phi}\dot{\Psi} \right] d^3x.\end{aligned}$$

# Final Remarks and future work

- We presented a covariant formulation to describe the dynamics of field theories, a notion of covariant phase space and a symplectic structure.
- We have seen how this covariant framework can be used to derive eventually useful results in field theories.
- As future perspectives, we want to obtain some general results in general relativity, using this covariant framework, particularly in vacuum spacetimes, as for example:
  - give a correct and general definition of angular momentum at null infinity;
  - study all the transformations that leave  $\omega$  invariant, and see if these transformations belong to the BMS group of symmetries or not.

# Final Remarks and future work

- We presented a covariant formulation to describe the dynamics of field theories, a notion of covariant phase space and a symplectic structure.
- We have seen how this covariant framework can be used to derive eventually useful results in field theories.
- As future perspectives, we want to obtain some general results in general relativity, using this covariant framework, particularly in vacuum spacetimes, as for example:
  - give a correct and general definition of angular momentum at null infinity;
  - study all the transformations that leave  $\omega$  invariant, and see if these transformations belong to the BMS group of symmetries or not.

# Final Remarks and future work

- We presented a covariant formulation to describe the dynamics of field theories, a notion of covariant phase space and a symplectic structure.
- We have seen how this covariant framework can be used to derive eventually useful results in field theories.
- As future perspectives, we want to obtain some general results in general relativity, using this covariant framework, particularly in vacuum spacetimes, as for example:
  - give a correct and general definition of angular momentum at null infinity;
  - study all the transformations that leave  $\omega$  invariant, and see if these transformations belong to the BMS group of symmetries or not.

# Final Remarks and future work

- We presented a covariant formulation to describe the dynamics of field theories, a notion of covariant phase space and a symplectic structure.
- We have seen how this covariant framework can be used to derive eventually useful results in field theories.
- As future perspectives, we want to obtain some general results in general relativity, using this covariant framework, particularly in vacuum spacetimes, as for example:
  - give a correct and general definition of angular momentum at null infinity;
  - study all the transformations that leave  $\omega$  invariant, and see if these transformations belong to the BMS group of symmetries or not.

# Final Remarks and future work

- We presented a covariant formulation to describe the dynamics of field theories, a notion of covariant phase space and a symplectic structure.
- We have seen how this covariant framework can be used to derive eventually useful results in field theories.
- As future perspectives, we want to obtain some general results in general relativity, using this covariant framework, particularly in vacuum spacetimes, as for example:
  - give a correct and general definition of angular momentum at null infinity;
  - study all the transformations that leave  $\omega$  invariant, and see if these transformations belong to the BMS group of symmetries or not.

Thank you for your attention!